

A minimum variance unbiased (generalized) estimator of total sensitivity indices: an illustration to a flood risk model

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- Context: better understand complex models wrt their inputs

$$Y = \mathcal{M}(X_1, X_2, \dots, X_d)$$

- characterize interactions among inputs
- identify inputs that have the great effects on the model
- Interest in Variance-based-Sensitivity Analysis [1,2,3] and Multivariate Sensitivity Analysis [4,5]
 - objective way to evaluate the impact of input factors on the model output (s)
 - provide total sensitivity indices (TSIs) or total-effect variances (TEVs)

- Objective: provide new estimators of TEV and TSI and their statistical properties
- Outline
 - 1 Our new estimator of a TEV that generalizes Saltelli-Jansen's estimator
 - 2 Some properties of the generalized estimator of a TSI
 - 3 Illustration to a flood risk model
 - 4 Conclusion

1. New estimator of a total-effect variance (TEV)

Model

$$Y = \mathcal{M}(X_1, X_2, \dots, X_d)$$

with $\mathbf{X} = (X_1, \dots, X_d) = (\mathbf{X}_u, \mathbf{X}_{\sim u})$, d independent inputs (A1)

Sobol-Hoeffding's decomposition: if $\mathbb{E}(f^2(\mathbf{X})) < +\infty$ (A2),

$$\mathcal{M}(\mathbf{X}) = \mathcal{M}_0 + \sum_j^d \mathcal{M}_j(X_j) + \sum_{i < j}^d \mathcal{M}_{ij}(X_i, X_j) + \dots (1.1)$$

Re-organized Sobol-Hoeffding's decomposition ([6,7])

$$\mathcal{M}(\mathbf{X}) = \mathcal{M}_0 + g_u(\mathbf{X}) + h_{\sim u}(\mathbf{X}_{\sim u}), \quad (1.2)$$

with $g_u(\mathbf{X}) = \sum_{v, v \cap u \neq \emptyset} \mathcal{M}_v(\mathbf{X}_u)$ and $\mathbb{E}[g_u^2(\mathbf{X})] = D_u^{tot}$ (TEV).

1. New estimator of a total-effect variance (TEV)

It is known that the TEV of \mathbf{X}_u is ([8,9]):

$$D_u^{tot} = \mathbb{E} \left([\mathcal{M}(\mathbf{X}) - \mathbb{E}_{\mathbf{X}_u} [\mathcal{M}(\mathbf{X})]]^2 \right). \quad (1.3)$$

Estimator of the TEV of \mathbf{X}_u

Definition

Consider p independent variables $(\mathbf{X}_u^{(1)}, \mathbf{X}_{\sim u}), \dots, (\mathbf{X}_u^{(p)}, \mathbf{X}_{\sim u})$ from the probability measure $\mu(\mathbf{X})$. We define the kernel

$$K \left(\mathbf{X}_u^{(1)}, \dots, \mathbf{X}_u^{(p)}, \mathbf{X}_{\sim u} \right) = \frac{1}{(p-1)p^2} \sum_{k=1}^p \left(\sum_{\substack{j=1 \\ j \neq k}}^p [\mathcal{M}(\mathbf{X}_u^{(k)}, \mathbf{X}_{\sim u}) - \mathcal{M}(\mathbf{X}_u^{(j)}, \mathbf{X}_{\sim u})] \right)^2.$$

We use $\sigma_{p,1}^2 = \text{Var} \left[K \left(\mathbf{X}_u^{(1)}, \dots, \mathbf{X}_u^{(p)}, \mathbf{X}_{\sim u} \right) \right]$ if $\mathbb{E} [\mathcal{M}(\mathbf{X})^4] < \infty$ (A3).

1. New estimator of a total-effect variance (TEV)

Theorem

Consider independent samples $(\mathbf{X}_{i,u}^{(1)}, \mathbf{X}_{i,\sim u}), \dots, (\mathbf{X}_{i,u}^{(p)}, \mathbf{X}_{i,\sim u})$ $i = 1, \dots, m$ from $\mu(\mathbf{X})$. If A1, A3 hold then the estimator

$$\widehat{D}_u^{tot} = \frac{1}{m} \sum_{i=1}^m K \left(\mathbf{X}_{i,u}^{(1)}, \dots, \mathbf{X}_{i,u}^{(p)}, \mathbf{x}_{i,\sim u} \right)$$

i) is unbiased:

$$\mathbb{E} \left[\widehat{D}_u^{tot} \right] = D_u^{tot}, \quad (1.4)$$

ii) has the minimum variance and optimal rate of convergence:

$$m \mathbb{E} \left(\widehat{D}_u^{tot} - D_u^{tot} \right)^2 = \sigma_{p,1}^2, \quad (1.5)$$

iii) follows asymptotically a normal distribution:

$$\sqrt{m} \left(\widehat{D}_u^{tot} - D_u^{tot} \right) \xrightarrow{\mathcal{D}} \mathcal{N} \left(0, \sigma_{p,1}^2 \right). \quad (1.6)$$

1. New estimator of a total-effect variance (TEV)

Proof

Ideas of the proof (comprehensive details are in [9]).

- i) Show that $\mathbb{E} \left[K \left(\mathbf{X}_u^{(1)}, \dots, \mathbf{X}_u^{(p)}, \mathbf{X}_{\sim u} \right) \right] = D_u^{tot}$.
- ii) Use the theory of U-statistics [10] to obtain the optimal rate, the minimum variance and the asymptotic distribution.

2. Some properties of the estimator of a TSI

Theorem

Consider independent samples $(\mathbf{X}_{i,u}^{(1)}, \mathbf{X}_{i,\sim u}), \dots, (\mathbf{X}_{i,u}^{(p)}, \mathbf{X}_{i,\sim u})$ $i = 1, \dots, m$ from $\mu(\mathbf{X})$. If A1 and A3 hold then the generalized estimator of S_{T_u} is:

$$\widehat{S}_{T_u} = \frac{\widehat{D}_u^{tot}}{\widehat{D}}, \quad (1.7)$$

with \widehat{D} the estimator of the model variance (D).

The estimator \widehat{S}_{T_u} i) is consistent:

$$\widehat{S}_{T_u} \xrightarrow{\mathcal{P}} S_{T_u}, \quad (1.8)$$

ii) follows asymptotically a normal distribution

$$\sqrt{m} \left(\widehat{S}_{T_u} - S_{T_u} \right) \xrightarrow{\mathcal{D}} \mathcal{N} \left(0, \frac{\sigma_{p,1}^2}{D^2} \right). \quad (1.9)$$

2. Some properties of the estimator of a TSI

Proof

Ideas of the proof (comprehensive details are in [9]).

For i): using Slutsky's theorem and the fact that $\widehat{D}_u^{tot} \xrightarrow{\mathcal{P}} D_u^{tot}$ and $\widehat{D} \xrightarrow{\mathcal{P}} D$, we have

$$\widehat{S}_{T_u} \xrightarrow{\mathcal{P}} S_{T_u}.$$

For ii): using Slutsky's theorem and the fact that

$\sqrt{m} \left(\widehat{D}_u^{tot} - D_u^{tot} \right) \xrightarrow{\mathcal{D}} \mathcal{N} \left(0, \sigma_{p,1}^2 \right)$ and $\sqrt{m} \left(\frac{1}{\widehat{D}} - \frac{1}{D} \right) \xrightarrow{\mathcal{P}} 0$ the result follows.

3. Illustration to a flood risk model

- Flood risk model ([11])

$$S = Z_v + H - H_d - C_b \quad \text{with} \quad H = \left(\frac{Q}{BK_s \sqrt{\frac{Z_m - Z_v}{L}}} \right)^{0.6},$$

H : maximal annual height of the river (in meters).

S : maximal annual overflow (in meters).

Flooding occurs when $S > 0$.

The model includes 8 input factors.

3. Illustration to a flood risk model

Table: Input factors of the flood risk model and their probability distributions [11]

Input	Description	Unit	Probability distribution
Q	Maximal annual flowrate	m^3/s	T. Gumbel $\mathcal{G}(1013, 558)$ on $[500, 3000]$
K_s	Strickler coefficient	-	T. normal $\mathcal{N}(30, 8)$ on $[15, +\infty[$
Z_v	River downstream level	m	Triangular $\mathcal{T}(49, 50, 51)$
Z_m	River upstream level	m	Triangular $\mathcal{T}(54, 55, 56)$
H_d	Dyke height	m	Uniform $\mathcal{U}[7, 9]$
C_b	Bank level	m	Triangular $\mathcal{T}(55, 55.5, 56)$
L	Length of the river stretch	m	Triangular $\mathcal{T}(4990, 5000, 5010)$
B	River width	m	Triangular $\mathcal{T}(295, 300, 305)$

3. Illustration to a flood risk model

- Quasi MC sampling of p -fold input values of type $m \times d$

$$\mathcal{X}_1 = \begin{pmatrix} x_{11}^{(1)} & \dots & x_{1j}^{(1)} & \dots & x_{1d}^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{m1}^{(1)} & \dots & x_{mj}^{(1)} & \dots & x_{md}^{(1)} \end{pmatrix} \dots \mathcal{X}_p = \begin{pmatrix} x_{11}^{(p)} & \dots & x_{1j}^{(p)} & \dots & x_{1d}^{(p)} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{m1}^{(p)} & \dots & x_{mj}^{(p)} & \dots & x_{md}^{(p)} \end{pmatrix}$$

For any input X_j , replace the j^{th} column of \mathcal{X}_1 with the j^{th} column of $\mathcal{X}_2, \dots, \mathcal{X}_p$.

$$\mathcal{X}_1 = \begin{pmatrix} x_{11}^{(1)} & \dots & x_{1j}^{(1)} & \dots & x_{1d}^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{m1}^{(1)} & \dots & x_{mj}^{(1)} & \dots & x_{md}^{(1)} \end{pmatrix} \dots \mathcal{X}'_p = \begin{pmatrix} x_{11}^{(1)} & \dots & x_{1j}^{(p)} & \dots & x_{1d}^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{m1}^{(1)} & \dots & x_{mj}^{(p)} & \dots & x_{md}^{(1)} \end{pmatrix}$$

- Computational cost for the estimation of d TSIs

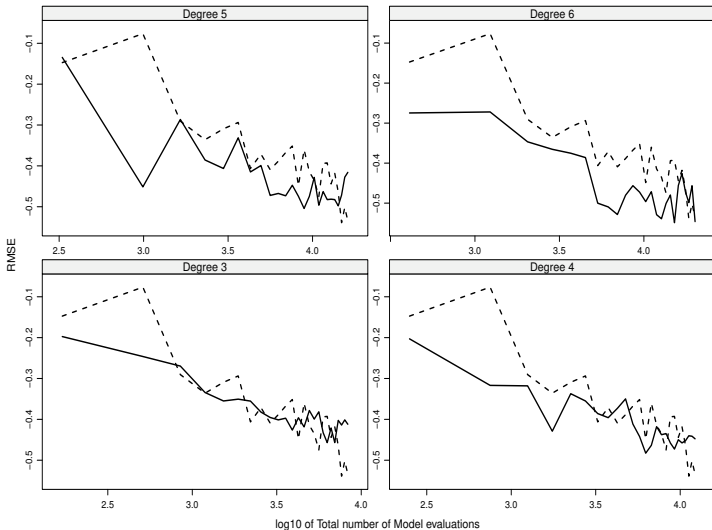
$$\text{cost} = m((p-1)d + 1)$$

3. Illustration to a flood risk model

- Comparison of different estimators of TSI ($p = 2, 3, 4, 5, 6$)
Saltelli-Jansen's estimator $p = 2$
Generalized estimator $p = 3, 4, 5, 6$
- Measure of accuracy: average of Root Mean Square Error (RMSE)

$$RMSE_d = \frac{1}{d} \sum_{j=1}^d \sqrt{\frac{1}{R} \sum_{r=1}^{R=30} \left(\widehat{S}_{T_j,r} - S_{T_j} \right)^2},$$

3. Illustration to a flood risk model



4. Conclusion

- Generalized estimator of total-effed variance
 - using p -fold input values
 - has minimum variance and is unbiased
 - reaches the optimal rate of convergence
- Generalized estimator of total sensitivity index
 - is consistent (convergence to the true value)
 - follows asymptotically a normal distribution
 - total cost is $m((p - 1)d + 1)$
- Illustration to a flood risk model
 - improve the estimation of TSIs when $p = 6$
- Perspective
 - the value of p depends on the model
 - find a way to determine p for a given model

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Thank for your attention !