

# **Global sensitivity analysis of models with correlated inputs and models with constraints**

S. Kucherenko, O.V. Klymenko, N. Shah  
*Imperial College London*  
*s.kucherenko@imperial.ac.uk*

## Outline

1. Global Sensitivity Analysis (GSA) and Sobol' Sensitivity Indices for case of independent inputs
2. Sobol' Sensitivity Indices for case of dependent inputs
3. Correlated inputs
4. Constrained Global Sensitivity Analysis (cGSA)
5. Conclusions

## ANOVA decomposition and Sensitivity Indices

Consider a model

$x$  is a vector of input variables

$f(x)$  is square integrable

$$Y = f(X)$$

$$X = (X_1, X_2, \dots, X_n) \in H^n$$

$$0 \leq X_i \leq 1$$

ANOVA decomposition is unique if **variables are independent**

$$Y = f(X) = f_0 + \sum_{i=1}^n f_i(X_i) + \sum_i \sum_{j>i} f_{ij}(X_i, X_j) + \dots + f_{1,2,\dots,n}(X_1, X_2, \dots, X_n),$$

$$\int_0^1 f_{i_1 \dots i_s}(X_{i_1}, \dots, X_{i_s}) dX_{i_p} = 0, \quad \forall p, 1 \leq p \leq s, \rightarrow \int_0^1 f_{i_1 \dots i_s} f_{i_1 \dots i_l} dX_{i_p} dX_{i_l} = 0, \quad \forall i_p \neq i_l$$

Variance decomposition:

$$D = \sum_i D_i + \sum_{i,j} D_{ij} + \dots + D_{1,2,\dots,n}$$

Sobol' SI:

$$1 = \sum_{i=1}^n S_i + \sum_{i<j} S_{ij} + \sum_{i<j<l} S_{ijl} + \dots + S_{1,2,\dots,n}$$

■ *Definition:*

$$S_{i_1 \dots i_s} = D_{i_1 \dots i_s} / D$$

$$D_{i_1 \dots i_s} = \int_0^1 f_{i_1 \dots i_s}^2(x_{i_1}, \dots, x_{i_s}) dx_{i_1}, \dots, x_{i_s} \quad \text{- partial variances}$$

$$D = \int_0^1 (f(x) - f_0)^2 dx \quad \text{- total variance}$$

■ *Sensitivity indices for subsets of variables:*  $x = (y, z)$

$$D_y = \sum_{s=1}^m \sum_{(i_1, \dots, i_s) \in K} D_{i_1, \dots, i_s}$$

*Total variance for a subset:*  $(D_y^T)^2 = D - D_z$

□ *Corresponding global sensitivity indices:*

$$S_y = \sigma_y^2 / \sigma^2, \quad S_y^T = D_y^T / D.$$

GSA is used for:

- identification of key parameters whose uncertainty most affects the output
- decreasing problem dimensionality

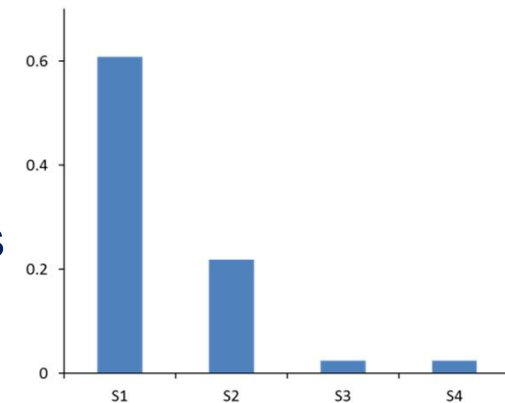
Direct formulas: Sobol' 1990, 2001, 2007

Evaluation of Sobol' SI is reduced to high-dimensional integration using MC/QMC methods

Further improvements - allow a reduced number of function evaluations compared to alternatives: Saltelli 2002, 2010

S. Kucherenko 2002, 2007, 2011, 2016

A. Owen 2012, 2013



What if inputs are not independent ?

- 1) ANOVA decomposition is not unique;
- 2) Direct Sobol' formulas are not valid

## Sobol' SI in the case of dependent inputs

Consider two subsets of variables:  $y = (x_{i_1}, \dots, x_{i_s})$ ,  $1 \leq s < n$ ,  $z = (x_{i_{s+1}}, \dots, x_{i_n})$   
so that  $x = (y, z)$ ,  $x \sim p(x_1, \dots, x_n)$

General decomposition:  $D = D_y[E_z(f(y, \bar{z}) | y)] + E_y[D_z(f(y, \bar{z}) | y)]$

First-order (main) effect index

$$S_y = \frac{D_y[E_z(f(y, \bar{z}))]}{D}$$

Total effect index of subset  $y$

$$S_y^T = \frac{E_z[D_y(f(\bar{y}, z))]}{D} = \frac{D - D_z[E_y(f(\bar{y}, z))]}{D}$$

## Sobol' Sensitivity Indices

First-order (main) effect index of subset of variables  $y = (x_{i_1}, \dots, x_{i_s})$ ,  $1 \leq s < n$   
 $[z = (x_{i_{s+1}}, \dots, x_{i_n})$  so that  $x = (y, z)]$

$$S_y = \frac{1}{D} \left[ \int_{H^s} p(y) dy \left[ \int_{H^{n-s}} f(y, \bar{z}) p(y, \bar{z} | y) d\bar{z} \right]^2 - f_0^2 \right]$$

$$S_y = \frac{1}{D} \left[ \int_{H^n} f(y', z') p(y', z') dy' dz' \left[ \int_{H^{n-s}} f(y', \hat{z}) p(y', \hat{z} | y') d\hat{z} - \int_{H^n} f(y, z) p(y, z) dy dz \right]^2 \right]$$

Total effect index of subset  $y$

$$S_y^T = 1 - \frac{1}{D} \left[ \int_{H^{n-s}} p(z) dz \left[ \int_{H^s} f(\bar{y}, z) p(\bar{y}, z | z) d\bar{y} \right]^2 - f_0^2 \right]$$

$$S_y^T = \frac{1}{2D} \int_{H^{n+s}} [f(y, z) - f(\bar{y}', z)]^2 p(y, z) p(\bar{y}', z | z) dy d\bar{y}' dz$$

Requires sampling from multivariate probability distributions ( $p(y)$ ,  $p(y, \bar{z} | y)$ , etc)

## Copula. Uniform distributions

$u = u_1, \dots, u_n$ ,  $u_i \in [0, 1]$ ,  $i = 1, \dots, n$ ,  $\Sigma_u$  - correlation matrix .

Gaussian copula function:

$$C(u_1, \dots, u_n; \Sigma_u) = F_n(F^{-1}(u_1), \dots, F^{-1}(u_n); \Sigma)$$

$F_n(\xi)$  - n-variate cumulative normal distribution function (NDF)

$F(\xi_i)$  – univariate NDF.

$F^{-1}$  - inverse NDF

$\bar{u}$  (independent uniform)  $\rightarrow \bar{\xi}$  (independent normal)

$\rightarrow \xi$  (dependent normal,  $\Sigma$ )  $\rightarrow u$  (dependent uniform,  $\Sigma_u$ )

(Require mapping  $\Sigma_u \rightarrow \Sigma$ )

$$u = T(\bar{u})$$

We can also use the inverse transformation

$$\bar{u} = T^{-1}(u)$$



## Copula. Arbitrary distributions

In a general case of arbitrary distributed r.v.  $X$  with  $\Sigma_x$   
and cumulative marginal distribution functions  $G_i(X_i)$

Gaussian copula function:

$$C(G_1(X_1), \dots, G_n(X_n); \Sigma_x) = F_n(F^{-1}(G_1(X_1)), \dots, F^{-1}(G_n(X_n)); \Sigma)$$

$\bar{u}$  (independent uniform)  $\rightarrow \bar{\xi}$  (independent normal)

$\rightarrow \xi$  (dependent normal,  $\Sigma$ )  $\rightarrow X$  (dependent r.v.,  $\Sigma_x$ )

(Require mapping  $\Sigma_x \rightarrow \Sigma$ )

$$X = T(\bar{u})$$

We can also apply the inverse transformation

$$\bar{u} = T^{-1}(X)$$

Main effect SI:

$$S_y = \frac{1}{D} \left[ \int_{R^s} \Phi_s(y) dy \left[ \int_{R^{n-s}} f(\bar{G}_s^{-1}(\bar{F}_s(y)), \bar{G}_{n-s}^{-1}(\bar{F}_{n-s}(z))) \Phi_{n-s}(y, z | y) dz \right. \right. \\ \left. \left. \int_{R^{n-s}} f(\bar{G}_s^{-1}(\bar{F}_s(y)), \bar{G}_{n-s}^{-1}(\bar{F}_{n-s}(\bar{z}'))) \Phi_{n-s}(y, \bar{z}' | y) d\bar{z}' \right] - f_0^2 \right],$$

Total order effect SI:

$$S_y^T = \frac{1}{2D} \int_{R^{n+s}} [f(\bar{G}_s^{-1}(\bar{F}_s(y)), \bar{F}_{n-s}(z)) - f(\bar{G}_s^{-1}(\bar{F}_s(\bar{y}')), \bar{G}_{n-s}^{-1}(\bar{F}_{n-s}(z)))]^2 \cdot \\ \cdot \Phi_{n-s}(z) \Phi_s(y, z | z) \Phi_s(\bar{y}', z | z) dy d\bar{y}' dz.$$

Here

$$\bar{G}_s^{-1}(\bar{F}_s(y)) = (G_1^{-1}(F(x_1)), \dots, G_s^{-1}(F(x_s))),$$

$$\Phi_n(x) = \frac{1}{(2\pi)^{n/2} \sqrt{|\Sigma|}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

## Correlated Inputs. Gaussian additive model

- Model

*Inputs are  
Gaussians*

$$Y = f(X_1, X_2, X_3) = X_1 + X_2 + X_3$$

- Correlation matrix

$$\Sigma = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \rho\sigma \\ 0 & \rho\sigma & 1 \end{pmatrix}$$

- SI :

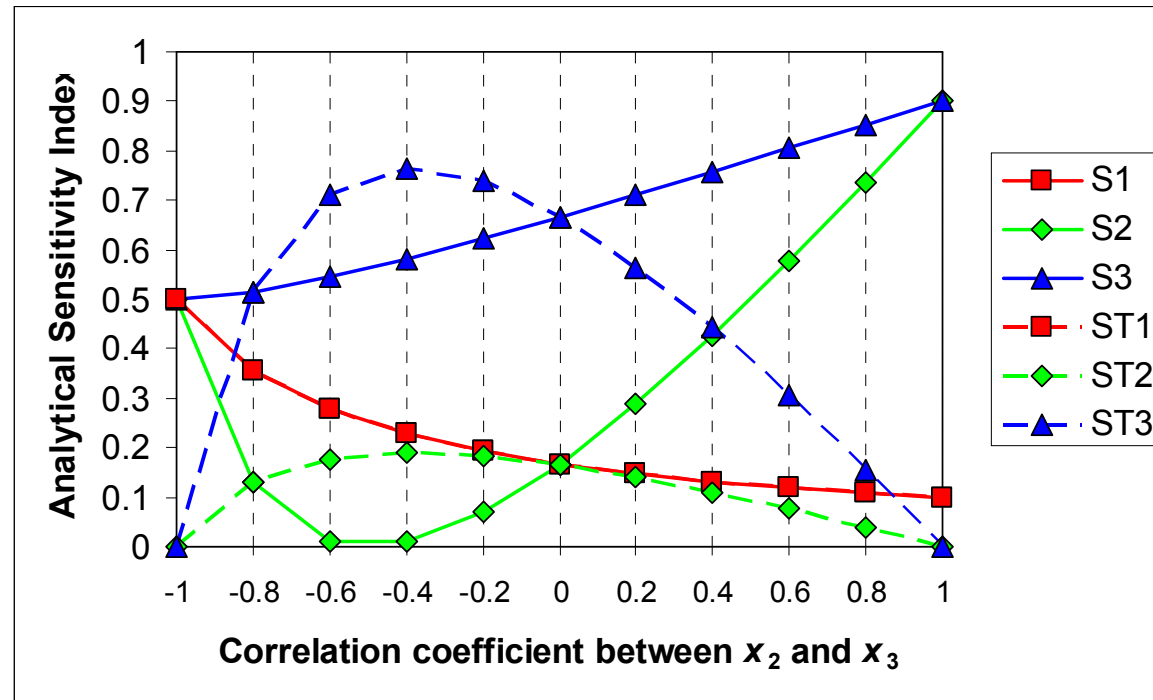
$$S_1 = \frac{1}{2 + \sigma^2 + 2\rho\sigma}, S_1^T = \frac{1}{2 + \sigma^2 + 2\rho\sigma};$$

$$S_2 = \frac{(1 + \rho\sigma)^2}{2 + \sigma^2 + 2\rho\sigma}, S_2^T = \frac{1 - \rho^2}{2 + \sigma^2 + 2\rho\sigma};$$

$$S_3 = \frac{(\sigma + \rho)^2}{2 + \sigma^2 + 2\rho\sigma}, S_3^T = \frac{\sigma^2(1 - \rho^2)}{2 + \sigma^2 + 2\rho\sigma}.$$

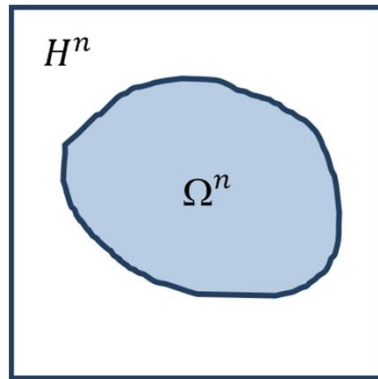
## Evolution of the first and total order indices at different values of correlation ratio $\rho$

Quasi MC sample size  $N = 2^{13}$



$$S_i^T \leq S_i, i = 2, 3 \text{ if } \rho \geq 0 \text{ or } \rho \leq -\frac{2\sigma}{\sigma^2 + 1}$$

$$S_2^T \rightarrow 0, S_3^T \rightarrow 0 \text{ if } |\rho| \rightarrow 1$$



Problem setting:  $f(x), x \in \Omega^n \subset H^n$

Joint PDF of inputs:  $p(x)$  in  $H^n \supset \Omega^n$

or  $p^\Omega(x)$  in  $\Omega^n$

Domain  $\Omega^n \subset H^n$  may be defined by a number of constraints:

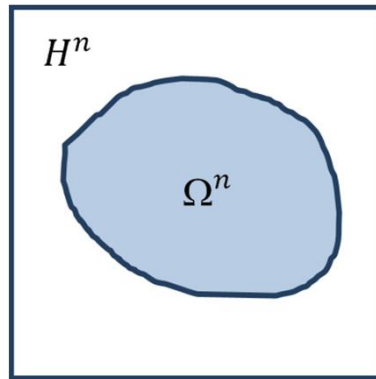
$$\Omega^n = \{x : g_m(x) \geq 0, m = 1, \dots, M\}$$

Constraint types:

- geometrical, physical, chemical, biological, economical, etc.
- 'input' (explicit) or 'output' (implicit) constraints:

$$f(x) \geq f_{\min} \quad \Rightarrow \quad g(x) = f(x) - f_{\min} \geq 0$$

# Acceptance-rejection method



Recall Sobol' SIs:

$$S_y = \frac{1}{D} \left[ \int_{H^s} p(y) dy \left[ \int_{H^{n-s}} f(y, \bar{z}) p(y, \bar{z} | y) d\bar{z} \right]^2 - f_0^2 \right]$$

$$S_y^T = 1 - \frac{1}{D} \left[ \int_{H^{n-s}} p(z) dz \left[ \int_{H^s} f(\bar{y}, z) p(\bar{y}, z | z) d\bar{y} \right]^2 - f_0^2 \right]$$

How to sample PDFs (marginal, conditional, ...) in non-rectangular domains?

$$p^\Omega(y, z) = \frac{p(y, z) I^\Omega(y, z)}{\int_{\Omega^n} p(y, z) dy dz} = \frac{p(y, z) I^\Omega(y, z)}{\bar{I}}$$

$$p^\Omega(y) = \int_{\Omega^n} p^\Omega(y, z) dz = \frac{1}{\bar{I}} \int_{H^{n-s}} p(y, z) I^\Omega(y, z) dz$$

$$p^\Omega(y, \bar{z} | y) = \frac{p^\Omega(y, z)}{p^\Omega(y)} = \frac{p(y, z) I^\Omega(y, z)}{\int_{H^{n-s}} p(y, z) I^\Omega(y, z) dz}$$

Set indicator:

$$I^\Omega(y, z) = \begin{cases} 1, & (y, z) \in \Omega^n \\ 0, & (y, z) \notin \Omega^n \end{cases}$$

Scaling factor:

$$\bar{I} = \int_{H^n} p(y, z) I^\Omega(y, z) dy dz$$

## Acceptance-rejection method

Explicit integral formulas for function mean and variance in  $\Omega$  :

$$f_0 = \int_{\Omega^n} f(y, z) p^\Omega(y, z) dy dz = \frac{1}{I} \int_{H^n} f(y, z) p(y, z) I^\Omega(y, z) dy dz$$

$$D = \int_{\Omega^n} f^2(y, z) p^\Omega(y, z) dy dz - f_0^2 = \frac{1}{I} \int_{H^n} f^2(y, z) p(y, z) I^\Omega(y, z) dy dz - f_0^2$$

...and first-order and total SI in  $\Omega$ :

$$S_y = \frac{1}{D} \left[ \int_{H^s} \frac{\left[ \int_{H^{n-s}} f(y, z) p^\Omega(y, z) dz \right]^2}{p^\Omega(y)} dy - f_0^2 \right]$$

$$S_y^T = 1 - \frac{1}{D} \left( \int_{H^{n-s}} \frac{\left[ \int_{H^s} f(y, z) p^\Omega(y, z) dy \right]^2}{p^\Omega(z)} dz - f_0^2 \right)$$

## Acceptance-rejection method

Modified formulas:

$$S_y = \frac{1}{D} \left[ \int_{H^n} f(y', z') p^\Omega(y', z') dy' dz' \left[ \int_{H^{n-s}} \frac{f(y', z)}{p^\Omega(y')} p^\Omega(y', z) dz - \int_{H^n} f(y, z) p^\Omega(y, z) dy dz \right] \right]$$

$$S_y^T = \frac{1}{2D} \int_{H^n} \int_{H^s} [f(y, z) - f(y', z)]^2 p^\Omega(y, z) \frac{p^\Omega(y', z)}{p^\Omega(z)} dy dy' dz$$



MC estimators of function mean and total variance:

$$f_0 \approx \frac{1}{\bar{I} N} \sum_{l=1}^N f(y_l, z_l) I^\Omega(y_l, z_l) \quad D \approx \frac{1}{\bar{I} N} \sum_{l=1}^N [f(y_l, z_l) - f_0]^2 I^\Omega(y_l, z_l)$$

Scaling factor: 
$$\bar{I} \approx \frac{1}{N} \sum_{l=1}^N I^\Omega(y_l, z_l)$$

Double loop reordering (DLR) formula for first-order indices:

$$S_y \approx \frac{1}{D} \left[ \frac{1}{\bar{I} N_y} \sum_{j=1}^{N_y} \frac{F^2(y_j^A)}{p^\Omega(y_j^A)} - f_0^2 \right]$$

where

$$F(y_j^A) \approx \frac{1}{\bar{I} N_z} \sum_{k=1}^{N_z} f(y_{j_k}, z_{j_k}) I^\Omega(y_{j_k}, z_{j_k}) \quad p^\Omega(y_j^A) \approx \frac{1}{\bar{I} N_z} \sum_{k=1}^{N_z} I^\Omega(y_{j_k}, z_{j_k})$$

Sample is subdivided into  $N_y \approx \sqrt{N}$  'bins'

Total number of sample points:  $N_{\text{CPU}} = N = N_y N_z$

## Double loop reordering approach (DLR)

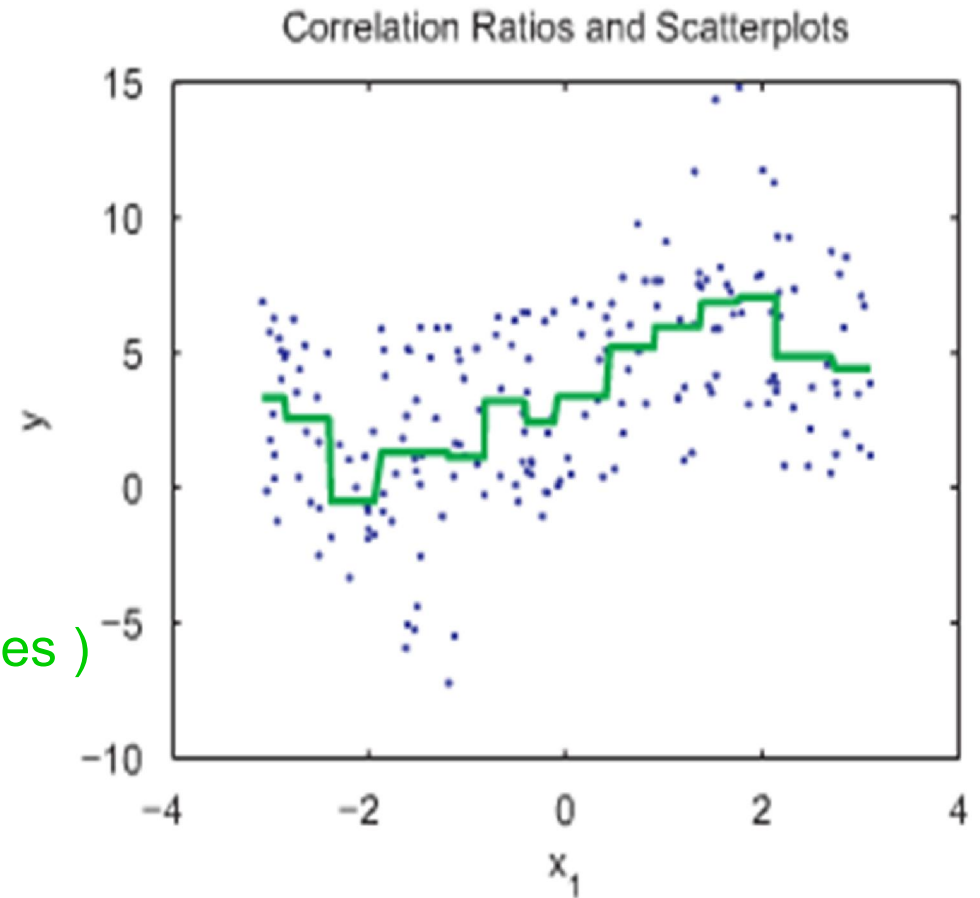
$$E_z(f(x_1, \bar{z}) | x_1)$$
$$S_{x_1} = \frac{D_{x_1}[E_z(f(x_1, \bar{z}) | x_1)]}{D}$$

Sort  $(x_1, Y = f)$

Divide space into M bins

Compute local mean values (green lines )

Estimate variance  $D_{x_1}$



## Monte Carlo estimators

Modified formulas for first-order and total indices:

$$S_y = \frac{1}{\bar{I}^2 DN} \sum_{l=1}^N \left( f(y'_l, z'_l) I(y'_l, z'_l) \left( \bar{I} \frac{f(y'_l, z_l) I(y'_l, z_l)}{p^\Omega(y'_l)} - f(y_l, z_l) I(y_l, z_l) \right) \right)$$

$$S_y^T = \frac{1}{2\bar{I} DN} \sum_{l=1}^N \left( f(y_l, z_l) I(y_l, z_l) - f(y'_l, z_l) I(y'_l, z_l) \right)^2 \frac{1}{p^\Omega(z_l)}$$

Total number of sample points:  $N_{\text{CPU}} = N(n + 2)$

## Test case 1. 2D g-function, linear constraint

Function:

$$g = \prod_{i=1}^n \frac{|4x_i - 2| + a_i}{1 + a_i}$$

$$n = 2, \quad a_1 = 0, \quad a_2 = 1$$

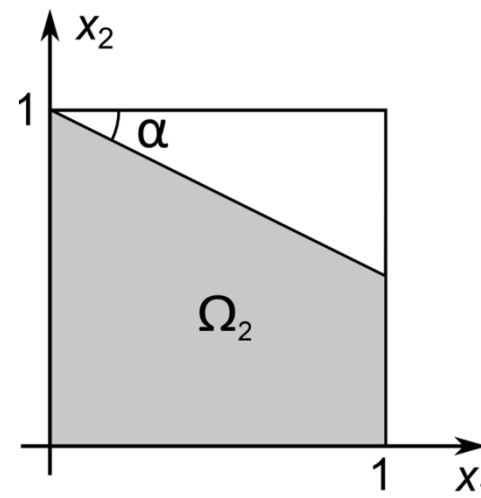
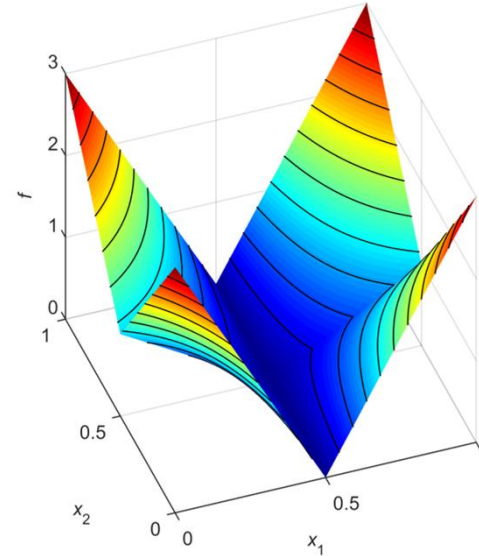
Joint PDF:

$$p(x_1, x_2) = 1$$

Permissible domain:

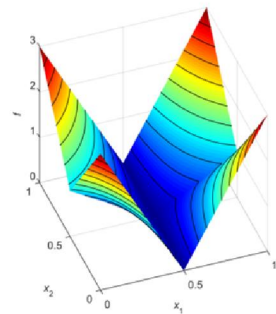
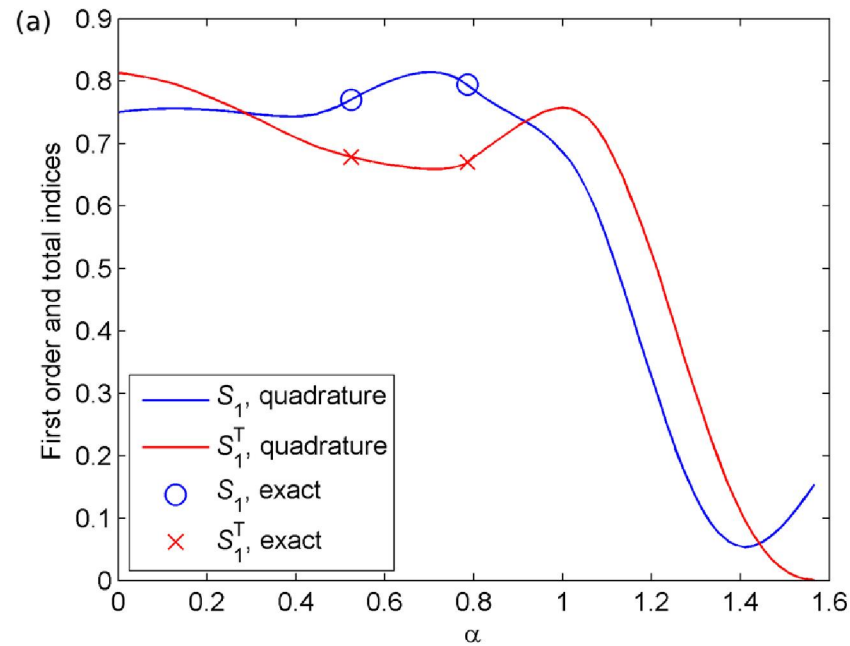
$$\Omega: \quad x_2 \leq 1 - x_1 \tan \alpha$$

$$0 \leq \alpha < \pi / 4$$

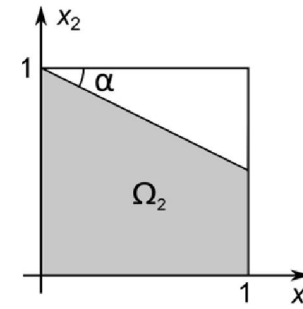
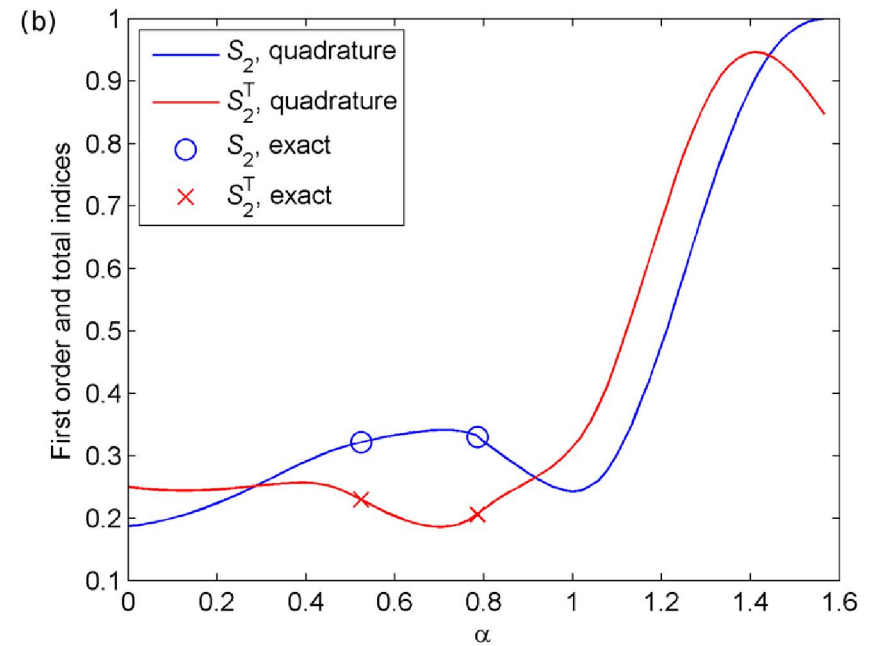


# Test case 1. 2D g-function, Sobol' SI's versus alfa

S1, S1\_Total



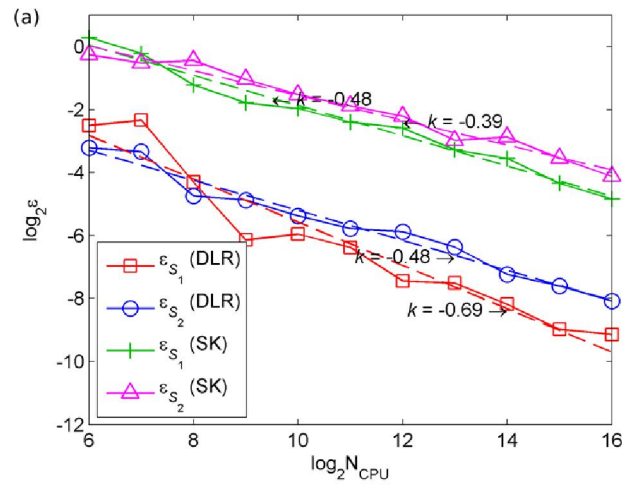
S2, S2\_Total



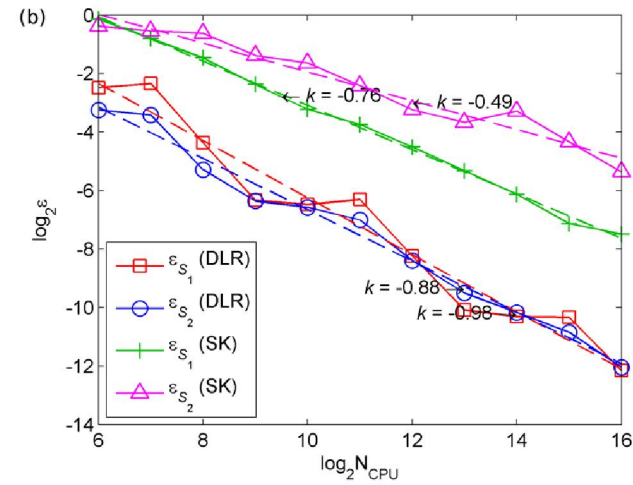
# Test case 1. 2D g-function, convergence plots

$\alpha = \pi/6$

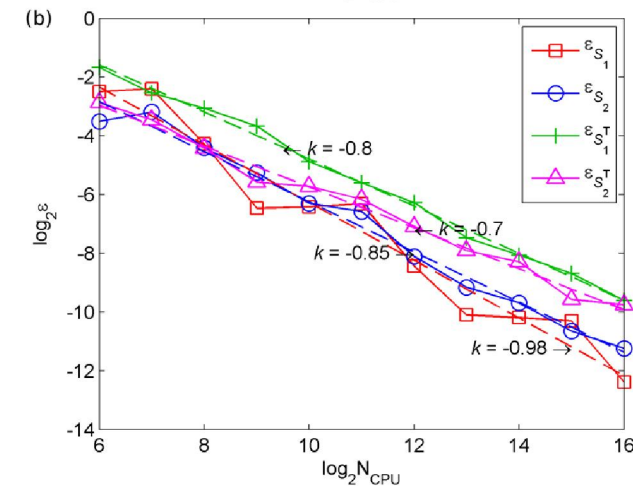
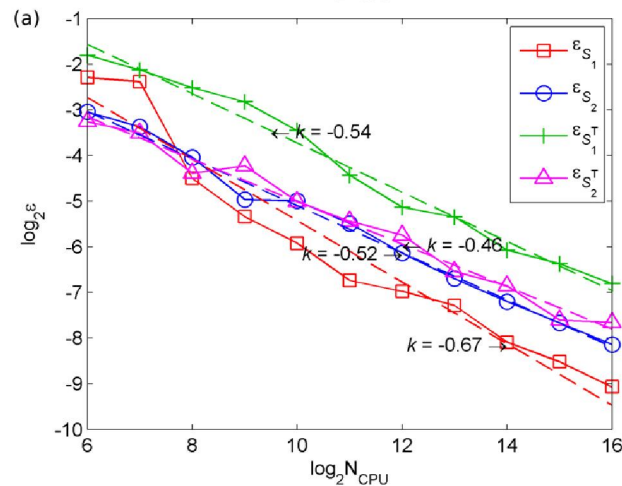
random sampling



Sobol' LDS



$S_i$  (DLR)  
 $S_i$  (modified)



$S_i$  (DLR)  
 $S_i^T$  (modified)

## Test case 2. 2D g-function, parabolic constraint

Function:

$$g = \prod_{i=1}^n \frac{|4x_i - 2| + a_i}{1 + a_i}$$

$$n = 2, \quad a_1 = 0, \quad a_2 = 1$$

Joint PDF:

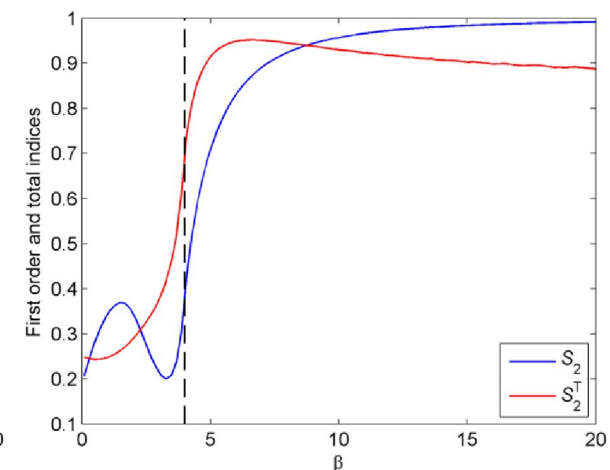
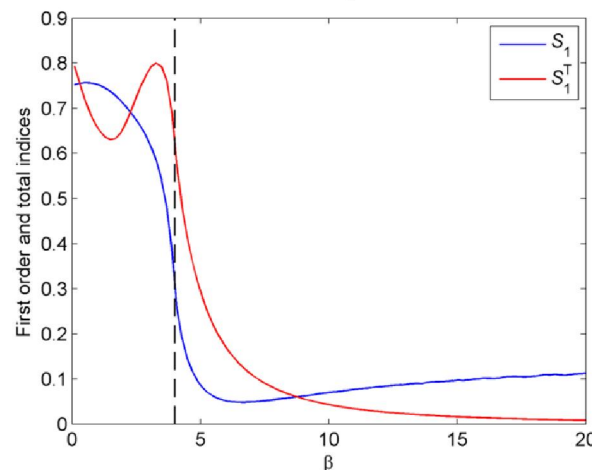
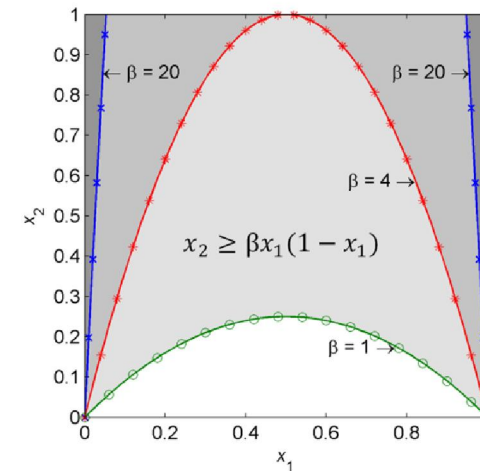
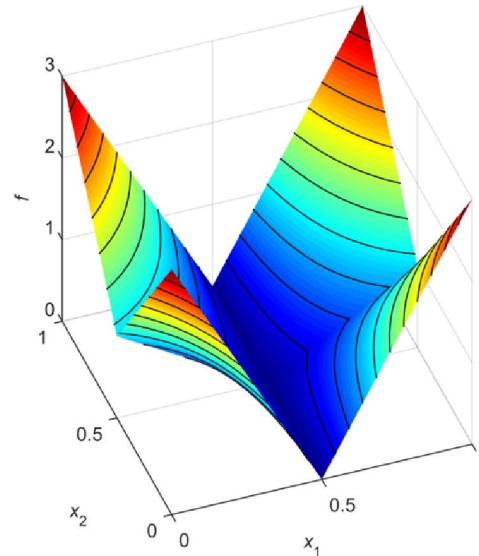
$$p(x_1, x_2) = 1$$

Permissible domain:

$$\Omega: \quad x_2 \geq \beta x_1(1 - x_1)$$

$$\beta > 0$$

Domain is disconnected  
for  $\beta > 4$ !



## Test case 3. 4D K-function, linear constraints

Function:

$$K = -x_1 + x_1x_2 - x_1x_2x_3 + x_1x_2x_3x_4 \quad \left( = \sum_{i=1}^n (-1)^i \prod_{j=1}^i x_j \right)$$

Permissible domains:

*Two important variables constrained:*

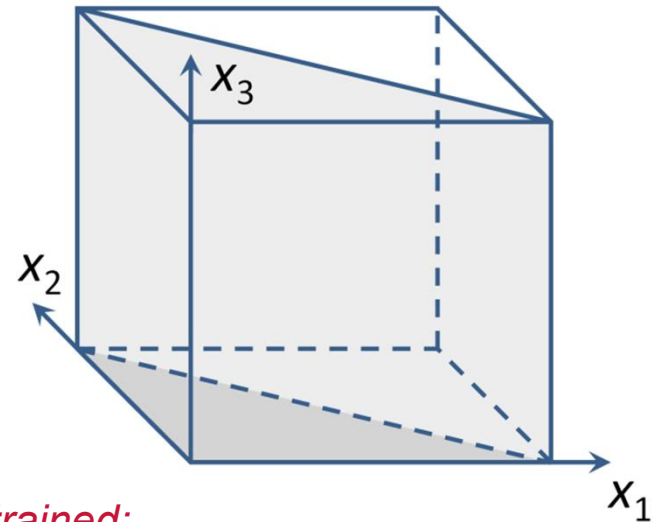
$$\Omega_1 : \quad x_1 + x_2 \leq 1$$

*Two unimportant variables constrained:*

$$\Omega_2 : \quad x_3 + x_4 \leq 1$$

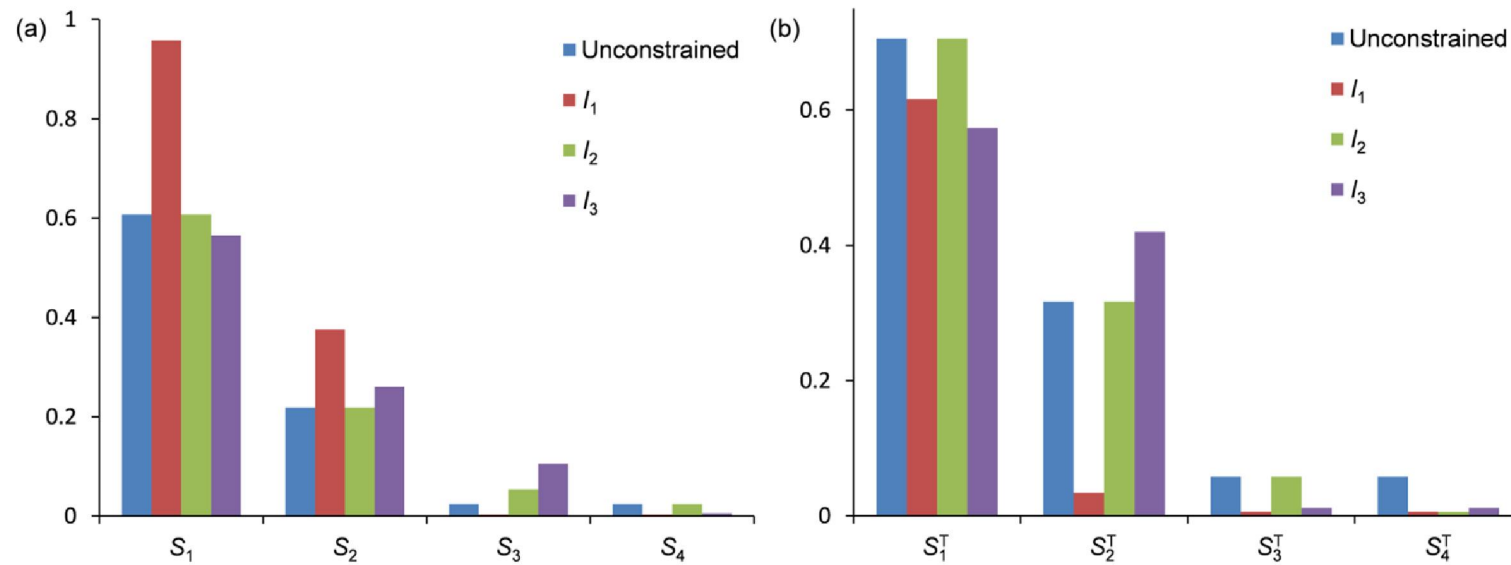
*One important and one unimportant variables constrained:*

$$\Omega_3 : \quad x_1 + x_3 \leq 1$$





## Test case 3. 4D K-function, Sobol SI's



$$\Omega_1 : x_1 + x_2 \leq 1$$

$$\Omega_2 : x_3 + x_4 \leq 1$$

$$\Omega_3 : x_1 + x_3 \leq 1$$

## Conclusions

- For the case of correlated inputs a gaussian copula based approach is proposed for sampling from arbitrary multivariate probability distributions.
- A large new class of models with inequality constraints can be analysed with cGSA
- Suggested acceptance-rejection formulas only require the knowledge of joint PDF and domain indicator function
- Further work is required on the interpretation of cGSA results
- *References*
  - S. Kucherenko, S. Tarantola, P. Annoni. Estimation of global sensitivity indices for models with dependent variables, *Computer Physics Communications*, V. 183 (2012) 937–946
  - S. Kucherenko, O.V. Klymenko, N. Shah Sobol' indices for problems defined in non-rectangular domains, *Submitted to Reliability Engineering and System Safety 2016*, <https://arxiv.org/abs/1605.05069>